

# Exponential Synchronization of the Hopfield Neural Networks with New Chaotic Strange Attractor

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**Abstract**—This paper studies the problems of exponential synchronization for the Hopfield neural networks with impulsive effects and Gui chaotic strange attractor. By employing the Lyapunov functional method of impulsive functional differential equations, some criteria for synchronization between two impulsive neural networks are derived. An illustrative example is provided to show the effectiveness and feasibility of the proposed method and results.

## 1 Introduction

Recently, the issue of controlled synchronization in complex dynamical networks has become a rather significant topic in both theoretical research and practical applications [1–3]. It is known that in theory and practice, impulsive control has been widely used to stabilize and synchronize chaotic systems. For example, Yang and Chua derived some sufficient conditions for the stabilization and synchronization of Chua's oscillators via impulsive control[4]; Xie, Wen and Li obtained sufficient conditions for the stabilization and synchronization of the Lorenz system via impulsive control with varying impulsive intervals[5]. The Hopfield neural networks with impulse effect are studied, where the criteria on the existence, uniqueness and global stability of periodic solution are obtained. Further, Gui chaos strange attractor was also found[6-10].

Motivated by the above discussions, the aim of this paper is to study the synchronization of Hopfield neural networks with a Gui chaotic strange attractor. By employing the Lyapunov-like stability theory of impulsive functional differential equations, some criteria for synchronization of Hopfield neural networks are derived.

The remainder of the paper is organized as follows: Section 2 describes the issue of synchronization of coupled impulsive systems with a Gui chaotic strange attractor. In Section 3, some sufficient conditions for the synchronization are derived by constructing suitable Lyapunov-like function. In Section 4, an illustrative example is given to show the effectiveness of the proposed method. Conclusions are given in Section 5.

## 2 Preliminaries and Problem Formulation

In this paper, we consider the following nonautonomous Hopfield neural networks model with impulses

$$\begin{cases} \dot{x}_i = -a_i x_i(t) + \sum_{j=1}^n b_{ij} f_j(x_j(t)) + c_i(t), \\ t > 0, t \neq t_k, \\ \Delta x_i(t_k) = x_i(t_k^+) - x_i(t_k^-) = -\gamma_{ik} x_i(t_k), \\ t > 0, t = t_k, \end{cases} \quad (1)$$

where  $\Delta x_i(t_k) = x_i(t_k^+) - x_i(t_k^-)$  are the impulses at moments  $t_k^+$  and  $t_1 < t_2 < \dots$  is a strictly increasing sequence such that  $\lim_{k \rightarrow \infty} t_k = +\infty$ ;  $x_i(t)$  corresponds to the state of the  $i$ th unit at time  $t$ ,  $a_i$  is a positive constant set;  $b_{ij}$  denotes the strength of the  $j$ th unit on the  $i$ th unit at time  $t$ ,  $c_i(t)$  denotes the external input on the  $i$ th neuron and  $f_j(x_j(t))$  denotes the output of the  $j$ th unit at time  $t$ .

As usual in the theory of impulsive differential equations, at the points of discontinuity  $t_k$  of the solution  $t \rightarrow x_i(t)$  we assume that  $x_i(t_k) \equiv x_i(t_k^-)$ . It is clear that, in general, the derivatives  $x_i'(t_k)$  do not exist. On the other hand, according to the first equality of (1) there exist the limits  $x_i'(t_k^\mp)$ .

According to the above convention, we assume  $x'_i(t_k) \equiv x'_i(t_k^-)$ .

Throughout this paper, we assume that:

(H1) Functions  $f_j(u)$  satisfy the Lipschitz condition, i.e., there are constants  $L_j > 0$  such that

$$|f_j(u_1) - f_j(u_2)| \leq L_j |u_1 - u_2|,$$

for all  $u_1, u_2 \in R = (-\infty, +\infty)$ .

(H2) There exists a positive integer  $p$ , such that

$$t_{k+p} = t_k + \omega, \gamma_{i(k+p)} = \gamma_{ik},$$

$i = 1, 2, \dots, n, k = 1, 2, \dots$

(H3)  $a_i > 0, c_i(t)$  are all continuous  $\omega$ -periodic functions.

As is known to all that (1) can exhibit chaotic phenomena [6-10]. In order to show it clearly, we give the following example.

Example 1. Consider a two-dimensional neural network with impulsive effects, which can be described by the following impulsive differential equations:

$$\begin{cases} \dot{x}_1 = -2x_1(t) + 0.56f_1(x_1(t)) + 0.48f_2(x_2(t)) \\ \quad + c_1(t), \quad t > 0, t \neq nT, \\ \dot{x}_2 = -2x_2(t) + 0.61f_1(x_1(t)) + 0.3f_2(x_2(t)) \\ \quad + c_2(t), \quad t > 0, t \neq nT, \\ x_1(nT^+) = (1 - \gamma_1)x_1(nT), \quad n = 1, 2, \dots, \\ x_2(nT^+) = (1 - \gamma_2)x_2(nT), \quad n = 1, 2, \dots, \end{cases} \quad (2)$$

where  $f_j(x_j) = 0.5(|x_j + 1| - |x_j - 1|)$ . Obviously,  $f_j(x)$  satisfy (H1). Now we investigate the influence of the period T of impulsive effect on the system (2). Set

$$c_1(t) = 2 - 0.5 \cos(1.5t),$$

$$c_2(t) = 2 + 0.5 \sin(0.5t),$$

$$T = 0.4\pi, \gamma_1 = 0.35, \gamma_2 = 0.2.$$

According to Theorems 1 and 2 in [6], the cellular neural network model (2) has a unique  $2\pi$ -periodic solution with 5-impulses in a period.

Furthermore, if  $T = 1$ , then (H2) isn't satisfied. Periodic oscillation of system (2) will be destroyed by impulses effect. Numeric results show that system (2) still has a global attractor which can be a Gui chaotic strange attractor. Every solutions of system (2) will finally tend to the new chaotic strange attractor which is useful in exponential synchronization (see Fig.1-3). □

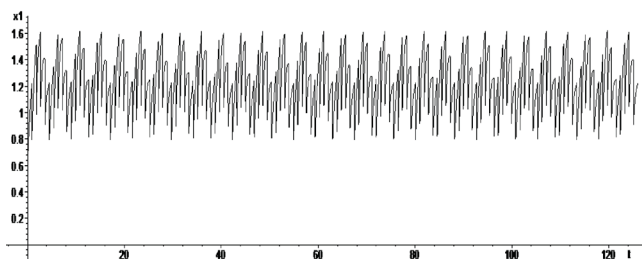


Figure 1. Time-series of the  $x_1(t)$  of system (2) with  $T = 1$

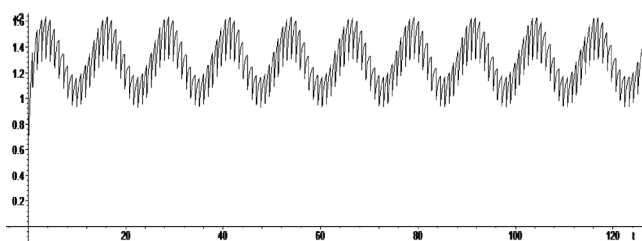


Figure 2. Time-series of the  $x_2(t)$  of system (2) with  $T = 1$

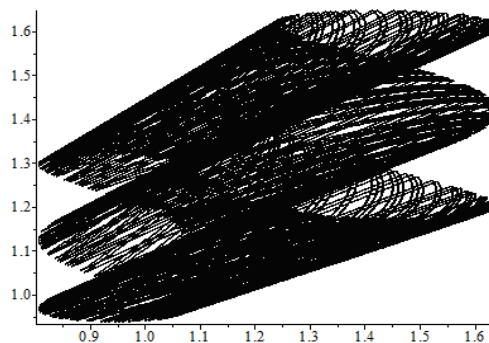


Figure 3. Phase portrait of Gui chaotic strange attractor of system (2)

For the purpose of synchronization, we introduce the response system that is driven by (1) via a set of signals

$$\begin{cases} \dot{y}_i = -a_i y_i(t) + \sum_{j=1}^n b_{ij} f_j(y_j(t)) + c_i(t), \\ \quad t > 0, t \neq t_k, \\ y_i(t_k^+) = x_i(t_k^-) - \gamma_{ik} y_i(t_k^-), \\ \quad i = 1, 2, \dots, n, k = 1, 2, \dots, \end{cases} \quad (3)$$

Let  $e_i(t) = y_i(t) - x_i(t)$  be the synchronization error,  $x_i(t)$  and  $y_i(t)$  are the state variables of drive system (1) and response system (3). The error system of the impulsive synchronization is given by

$$\begin{cases} \dot{e}_i = -a_i e_i(t) + \sum_{j=1}^n b_{ij}(e_j(t)), & t > 0, t \neq t_k, \\ e_i(t_k^+) = -\gamma_{ik} e_i(t_k^-), & i = 1, 2, \dots, n, k = 1, 2, \dots, \end{cases} \quad (4)$$

where  $g_j(e_j(t)) = f_j(y_j(t)) - f_j(x_j(t))$ . Note that the origin is the equilibrium point of system (4). If  $e_i(t)$  tends exponentially to origin in evolution, exponential synchronization between two systems would be realized. Our aim is to find some criteria on the impulsive gains  $\gamma_{ik}$  such that drive system (1) and respond system (3) are exponentially synchronized for any initial condition.

According to the assumption (H<sub>1</sub>),  $g_i(\cdot)$  possesses the following properties:

$$|g_j(e_j(t))| \leq L_j |e_j(t)|, \quad \text{and} \\ g_j(0) = 0, \quad j = 1, 2, \dots, n.$$

Throughout the paper, we denote

$$\|y(t) - x(t)\| = \sum_{j=1}^n |y_j(t) - x_j(t)|^r.$$

**Definition 1.** Systems (1) and (3) are said to be exponentially synchronized if there exist constants  $M \geq 1$  and  $\eta > 0$  such that

$$\|y(t) - x(t)\| = M \|y(0) - x(0)\| e^{-\eta t},$$

for any  $t \geq 0$ . Constant  $\eta$  is said to be the degree of exponential synchronization.

**Lemma 1.** Assume that  $x > 0, y > 0, p > 1, q > 1, 1/p + 1/q = 1$ , then the inequality

$$xy \leq \frac{1}{p} x^p + \frac{1}{q} y^q$$

holds (the inequality is called as Young inequality).

### 3 Main results

In this section, we investigate the exponential synchronization of system (1) and (3) by using Lyapunov like functional method.

**Theorem 1.** Under the assumption (H<sub>1</sub>), (H<sub>2</sub>) and (H<sub>3</sub>), the system (1) and (3) are exponentially synchronized, if there exist positive constants  $r > 1, w_i > 0$  and  $\sigma_{ij} \in R, i, j = 1, 2, \dots, n$ . such that

$$\begin{aligned} & -ra_i + (r-1) \sum_{j=1}^n L_j^{r(1-\sigma_{ij})/(r-1)} |b_{ij}|^{r(1-\sigma_{ij})/(r-1)} \\ & + \sum_{j=1}^n \frac{\lambda_j}{\lambda_i} L_i^{r\sigma_{ji}} |b_{ji}|^{r\sigma_{ji}} < 0, \quad i = 1, 2, \dots, n. \end{aligned} \quad (5)$$

**Proof.** By inequality (5), choose a small  $\varepsilon > 0$  such that

$$\begin{aligned} & r(\varepsilon - a_i) + (r-1) \sum_{j=1}^n L_j^{r(1-\sigma_{ij})/(r-1)} |b_{ij}|^{r(1-\sigma_{ij})/(r-1)} \\ & + \sum_{j=1}^n \frac{\lambda_j}{\lambda_i} L_i^{r\sigma_{ji}} |b_{ji}|^{r\sigma_{ji}} < 0, \quad i = 1, 2, \dots, n. \end{aligned}$$

Consider the following Lyapunov function:

$$V(e(t)) = \sum_{i=1}^n \lambda_i |e_i(t)|^r e^{r\varepsilon t}. \quad (6)$$

Calculating the upper right dini-derivative  $D^+V$  of  $V$  along the solution of system (4) at the continuous points  $t \neq t_k, t \geq 0$ , we have

$$\begin{aligned} D^+V(e(t)) &= \sum_{i=1}^n \lambda_i \left[ r\varepsilon e^{r\varepsilon t} |e_i(t)|^r + r e^{r\varepsilon t} |e_i(t)|^{r-1} \cdot \right. \\ & \quad \left. D^+ |e_i(t)| \right] \\ &= \sum_{i=1}^n \lambda_i \left[ r\varepsilon e^{r\varepsilon t} |e_i(t)|^r + r \text{sign}(e_i(t)) e^{r\varepsilon t} \cdot \right. \\ & \quad \left. |e_i(t)|^{r-1} \left( -a_i e_i(t) + \sum_{j=1}^n b_{ij} g_j(e_j(t)) \right) \right] \\ & \quad + r \sum_{j=1}^n |b_{ij}| |e_i(t)|^{r-1} |g_j(e_j(t))|. \end{aligned}$$

By Lemma 1, we have the following inequalities:

$$\begin{aligned} D^+V(e(t)) &\leq \sum_{i=1}^n \lambda_i e^{r\varepsilon t} \left[ r(\varepsilon - a_i) |e_i(t)|^r \right. \\ & \quad + (r-1) \sum_{j=1}^n L_j^{r(1-\sigma_{ij})/(r-1)} |b_{ij}|^{r(1-\sigma_{ij})/(r-1)} |e_i(t)|^r \\ & \quad \left. + \sum_{j=1}^n L_j^{r\sigma_{ij}} |b_{ij}|^{r\sigma_{ij}} |e_j(t)|^r \right] \\ &= \sum_{i=1}^n \lambda_i \left[ r(\varepsilon - a_i) + (r-1) \sum_{j=1}^n L_j^{r(1-\sigma_{ij})/(r-1)} \cdot \right. \\ & \quad \left. |b_{ij}|^{r(1-\sigma_{ij})/(r-1)} \right. \\ & \quad \left. + \sum_{j=1}^n \frac{\lambda_j}{\lambda_i} L_i^{r\sigma_{ji}} |b_{ji}|^{r\sigma_{ji}} \right] |e_i(t)|^r e^{r\varepsilon t} \leq 0, \\ & \quad t \geq 0, t \neq t_k. \end{aligned}$$

Also, we can calculate right limits of Lyapunov-like function  $V(e(t))$  at impulsive moments  $t_k$  as follows

$$\begin{aligned}
 V(e(t_k^+)) &= \sum_{i=1}^n \lambda_i |e_i(t_k^+)|^r e^{r\epsilon t_k^+} \\
 &= \sum_{i=1}^n |1 - \lambda_i| |e_i(t_k)|^r e^{r\epsilon t_k} \\
 &\leq \sum_{i=1}^n \lambda_i |e_i(t_k)|^r e^{r\epsilon t_k} = V(e(t_k)),
 \end{aligned}$$

which implies that

$$\begin{aligned}
 V(e(t)) &\leq V(e(0)) = \sum_{i=1}^n \lambda_i |e_i(0)|^r \\
 &= \sum_{i=1}^n \lambda_i |y_i(0) - x_i(0)|^r \\
 &\leq \max_{1 \leq i \leq n} \{\lambda_i\} \|y(0) - x(0)\|^r, \\
 &\text{for } t \geq 0.
 \end{aligned} \tag{7}$$

According to (6), we have

$$\begin{aligned}
 V(e(t)) &\geq \min_{1 \leq i \leq n} \{\lambda_i\} \sum_{i=1}^n |e_i(t)|^r e^{r\epsilon t} \\
 &\geq \min_{1 \leq i \leq n} \{\lambda_i\} e^{r\epsilon t} \|y(t) - x(t)\|^r.
 \end{aligned} \tag{8}$$

From (7) - (8), we can obtain

$$\|y(t) - x(t)\| \leq M \|y(0) - x(0)\| e^{-r\epsilon t}.$$

where  $M = \max_{1 \leq i \leq n} \{\lambda_i\} / \min_{1 \leq i \leq n} \{\lambda_i\} \geq 1$ . According to Definition 1, we conclude that the drive system (1) and the response system (3) are exponentially synchronized. This completes the proof. □

### 4 A Simulation Example

In this section, we give an example to illustrate the effectiveness of the results obtained in the previous sections. Consider a two-dimensional neural networks with impulsive effects.

Taking (2) as the drive system in Example 1. The response system is constructed as follows:

$$\begin{cases}
 \dot{y}_1 = -2y_1(t) + 0.56f_1(y_1(t)) \\
 \quad + 0.48f_2(y_2(t)) + c_1(t), & t \neq nT, \\
 \dot{y}_2 = -2y_2(t) + 0.61f_1(y_1(t)) \\
 \quad + 0.3f_2(y_2(t)) + c_2(t), & t \neq nT, \\
 y_1(nT^+) = x_1(nT^-) - \gamma_1 y_1(nT), n = 1, 2, \dots, \\
 y_2(nT^+) = x_2(nT^-) - \gamma_2 y_2(nT), n = 1, 2, \dots.
 \end{cases} \tag{9}$$

Then the error system of drive system (2) and response system (9) is constructed as follows:

$$\begin{cases}
 \dot{e}_1 = -2e_1(t) + 0.56g_1(e_1(t)) + 0.48g_2(e_2(t)), \\
 \dot{e}_2 = -2e_2(t) + 0.61g_1(e_1(t)) + 0.3g_2(e_2(t)), \\
 \quad t \neq nT, \\
 e_1(nT^+) = -\gamma_1 e_1(nT^-), \quad n = 1, 2, \dots, \\
 e_2(nT^+) = -\gamma_2 e_2(nT^-), \quad n = 1, 2, \dots.
 \end{cases} \tag{10}$$

Numeric results show that system (9) still has a Gui chaotic strange attractor<sup>[6-10]</sup>. The phase plot of Gui chaotic strange attractor of response system is shown in Fig. 4. It is easy to check the conditions in Theorem 1 are satisfied. Therefore, systems (2) and (9) exhibit exponential synchronization. Define  $e_i(t) = y_i(t) - x_i(t)$  and the errors (10) between systems (2) and (9) are depicted in Fig. 5.

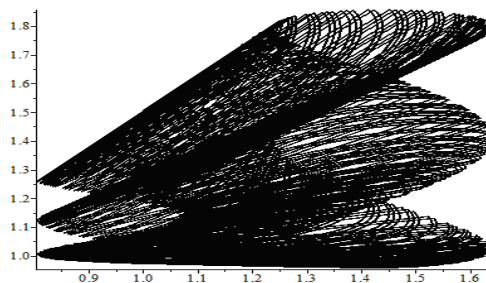


Figure 4. Phase portrait of Gui chaotic strange attractor of system (9)

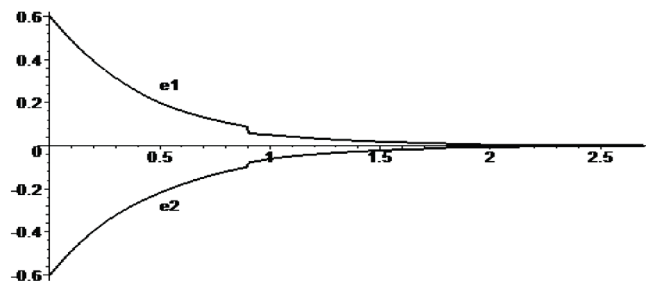


Figure 5. Synchronization errors between drive system (2) and response system (9)

### Conclusions

In this paper, the conditions for the exponential synchronization of a class of neural networks with impulsive effects are derived by utilizing Lyapunov functional method. A numerical simulation is given to show the effectiveness and feasibility of the proposed method. As far as we know, there is no paper to deal with such a problem.

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