

selected design variables, whilst the third one was set as constant.

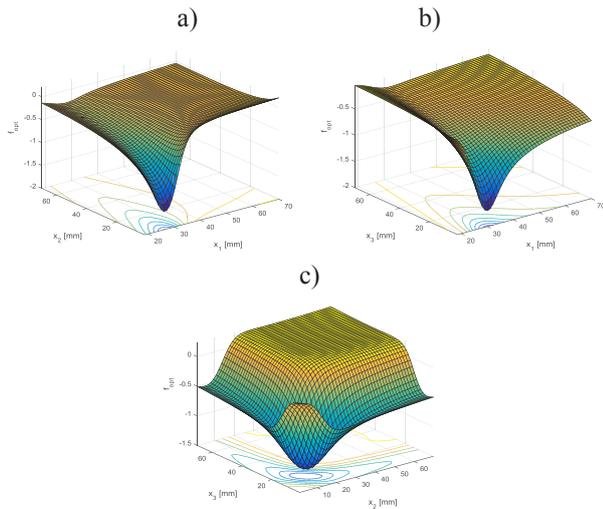


Fig. 2. Variations of objective function: a) vs. x_1 and x_2 , b) vs. x_1 and x_3 , c) vs. x_2 and x_3 .

2 Optimisation

Minimisation of (2) subject to (3) using the interior point (IP) algorithm ensures that neither design variable can leave the feasible region [4]. This is possible thanks to introduction of the logarithmic barrier function which modifies the original minimisation algorithm to [4]

$$\min_{\mathbf{x}} \left(f(\mathbf{x}) - \mu_k \sum_{i=1}^{n_g} \ln(z_i) \right) \quad (4)$$

$$\mathbf{g}(\mathbf{x}) - \mathbf{z} = 0, \quad \mathbf{z} \geq 0 \quad (5)$$

where μ_k is a barrier parameter which is calculated using formula in [4]. In the IP algorithm the optimisation problem is to find the stationary point of the following Lagrange function

$$L_{\mu}(\mathbf{y}_k, \mu_k) = f(\mathbf{x}) - \mu_k \sum_{i=1}^{n_g} \ln(z_i) + \boldsymbol{\pi}^T (\mathbf{g}(\mathbf{x}) - \mathbf{z}) \quad (6)$$

with $\boldsymbol{\pi}$ being the vector of Lagrange multipliers, which is carried out using the Newton-Raphson method [4].

3 Results

The starting points for the algorithm were selected using the Latin Hypercube sampling. From the 50 random solutions the three best ones, which fall into the area restricted by (3), are selected. The results of optimisation for such starting points are given in Tab.1.

Table 1. Results of optimisation.

Starting point \mathbf{x}_0	No. of iterations	Exec. time	Solution \mathbf{x}_{opt}
$[20.97 \ 4.03 \ 0.05]^T$	14	2.8 s	$[22.51 \ 10.22 \ 9.75]^T$
$[22.39 \ 7.82 \ 3.40]^T$	13	2.7 s	$[22.51 \ 10.22 \ 9.75]^T$
$[28.43 \ 11.04 \ 15.86]^T$	13	2.7 s	$[22.51 \ 10.22 \ 9.75]^T$

Fig. 3 shows the variations of (2) for the optimal solution as well as for the three other randomly selected initial designs. The most favoured optimal solution (due to high voltage at small displacement) is plotted using solid line. As one can notice the induced voltage was increased by some 20 per cent with respect to the best initial solution.

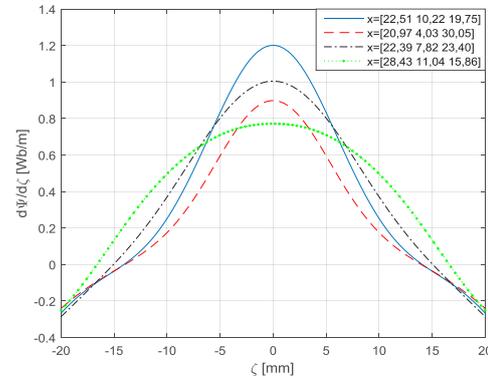


Fig. 3. Variations of flux linkage derivative for initial and optimal designs.

4 Conclusion

In this work the application of the interior point algorithm to maximisation of voltage induced in additional coils of a vibration energy harvester was presented. One important advantage of the method, beside a good numerical performance, is that in contrast to other tested local search algorithms, such as Powell, Jives-Hooke, Broyden-Fletcher-Goldfarb-Shanno, and conjugate gradient algorithms, it ensures that during evaluation of the objective function the design variables never leave the feasible region. This is very important advantage from the point of view of optimisation of physical structures, especially when the objective function is determined from numerical models such as the finite element models.

The results obtained in this work are the basis for development of new system which is currently under construction.

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